





A Verisk Business

Online Learning with Optimism and Delay

<u>Genevieve Flaspohler^{1,2}</u>, Francesco Orabona³, Judah Cohen⁴,

Soukayna Mouatadid⁵, Miruna Oprescu⁷, Paulo Orenstein⁶, and Lester Mackey⁷

MIT¹, Woods Hole Oceanographic Institution², Boston University³,

Atmospheric and Environmental Research⁴, University of Toronto⁵, IMPA⁶, Microsoft Research⁷





stituto de Matemática Pura e Aplicada



Sequential Decision-Making via Online Learning

- At time t:
- 1. Make play $\mathbf{w}_t \in \mathbf{W}$
- 2. Receive loss function ℓ_t from an adversarial environment
- 3. Pay $\ell_t(\mathbf{w}_t)$

Our objective is to do as well as the best constant play in retrospect.

$$\begin{array}{l} \operatorname{Regret}_{T} = \sup_{\mathbf{u} \in \mathbf{U}} \sum_{t=1}^{T} \frac{\ell_t(\mathbf{w}_t) - \ell_t(\mathbf{u})}{The \ \text{best } \underline{\mathbf{u}} \in \mathbf{U}} \sum_{t=1}^{T} \frac{\ell_t(\mathbf{w}_t) - \ell_t(\mathbf{u})}{The \ \text{loss of online}} \end{array}$$

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✓ Unbounded or unknown delays

Learning with delay is a special case of learning with optimism.

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Predictable/non-adversarial structure

e.g., contextual or side information.

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via a novel delay-as-optimism reduction.

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Optimistic hints

via a novel analysis of optimistic Theorem 5 (ODFTRL regret). If ψ is nonnegative, then, for all $\mathbf{u} \in \mathbf{W}$, the ODFTRL iterates \mathbf{w}_t satisfy

 $\operatorname{Regret}_{T}(\mathbf{u}) \leq \lambda \psi(\mathbf{u}) + \frac{1}{\lambda} \sum_{t=1}^{T} \mathbf{b}_{t,F} \quad for$ $\mathbf{b}_{t,F} \triangleq \operatorname{huber}(\|\mathbf{h}_{t} - \sum_{s=t-D}^{t} \mathbf{g}_{s}\|_{*}, \|\mathbf{g}_{t}\|_{*}).$

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The first optimal regret bound for general optimistic and delayed FTRL (and OMD).

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X Real-time operational use

e.g., continuous forecasting.

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via a novel analysis of optimistic learning the reveals increased robustness to hint errors.

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Hyper-parameter free

with hint learning and no tuning

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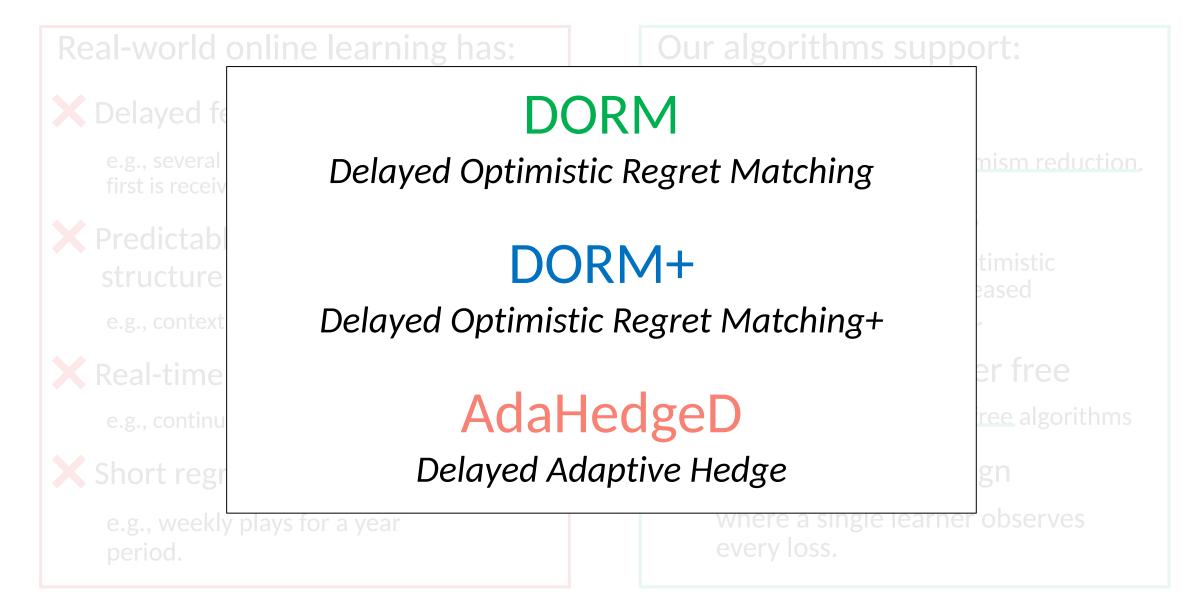
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\checkmark Non-replicated design

where a single learner observes every loss.

Delayed and Optimistic Online Learning



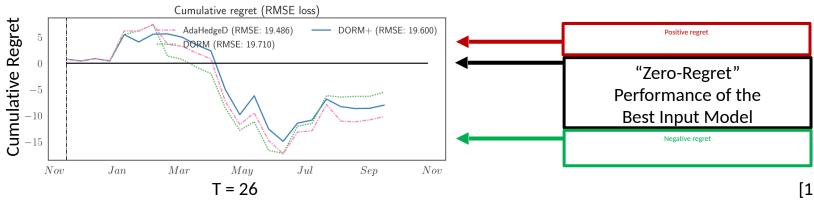
State-of-the-art Subseasonal Forecasting

What: Predicting the spatial distribution of temperature and precipitation 2 – 6 weeks out, w/applications in <u>agriculture and energy</u> [1].

Objective: Ensemble input models by playing weights: $\mathbf{w}_t \in \Delta$



Results: Using delayed and optimistic learners, we achieve negative regret in 3 of 4 subseasonal forecasting tasks.



[1] White et al., 2017, Meteorological Applications.







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