

Differential Equations and Arithmetic

Hossein Movasati

IMPA, Instituto de Matemática Pura e Aplicada, Brazil
www.impa.br/~hossein/

Hilbert's sixteen problem:

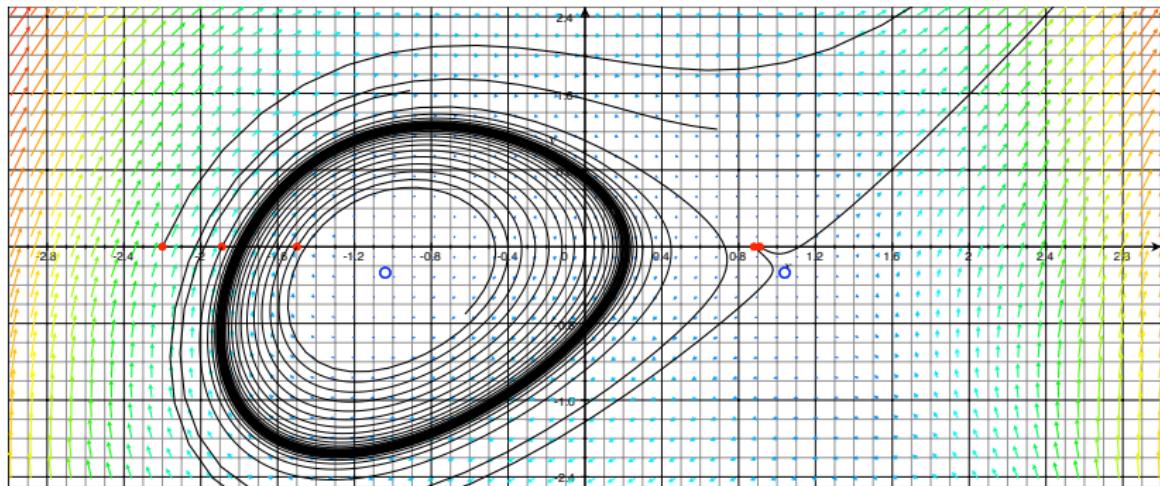


Figure: A limit cycle crossing $(x, y) \sim (-1.79, 0)$.

$$\mathcal{F} : \begin{cases} \dot{x} = 2y + \frac{x^2}{2} \\ \dot{y} = 3x^2 - 3 + 0.9y \end{cases}, \epsilon \in (\mathbb{R}, 0).$$

Center Problem:

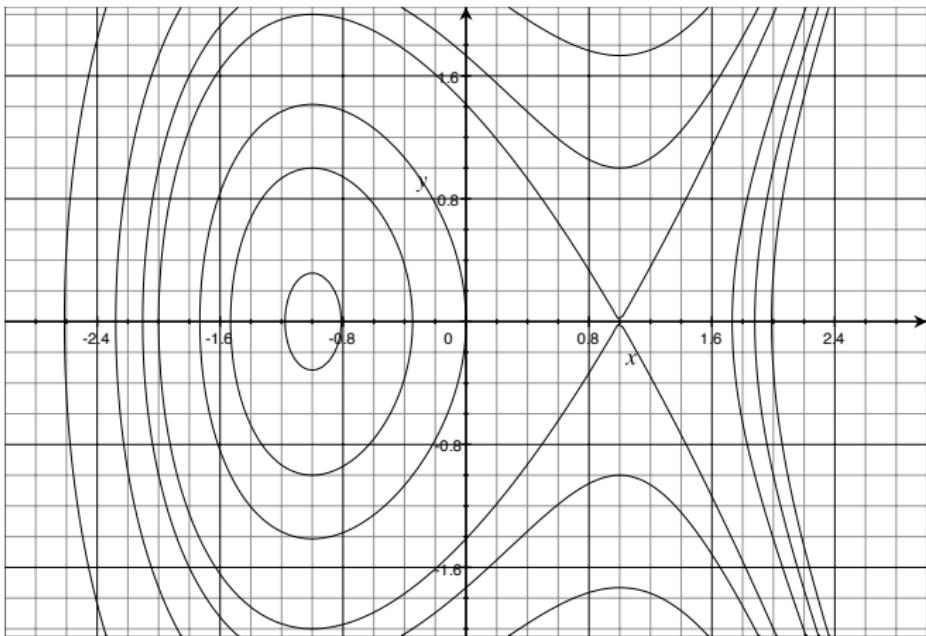


Figure: $f := y^2 - x^3 + 3x, f - t = 0, t = -1.9, -1, 0, 2, 3, 5, 10$

$$\begin{cases} \dot{x} = f_y \\ \dot{y} = -f_x \end{cases}.$$

1. Painlevé VI differential equation
2. Heun differential equation
3. Picard-Fuchs differential equations
4. Gauss hypergeometric equation and continued fractions
5. Darboux and Halphen differential equations
6. Bershadsky-Cecotti-Ooguri-Vafa anomaly equation
7. ...

Gauss-Manin connection:¹

Let $P(x) := 4(x - t_1)^3 + t_2(x - t_1) + t_3$. We have

$$\begin{pmatrix} d \left(\int \frac{dx}{\sqrt{P(x)}} \right) \\ d \left(\int \frac{x dx}{\sqrt{P(x)}} \right) \end{pmatrix} =$$

¹Carl Friedrich Gauss (1777-1855), Yuri Ivanovitch Manin, (1937-..)

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$$\begin{pmatrix} d \left(\int \frac{dx}{\sqrt{P(x)}} \right) \\ d \left(\int \frac{x dx}{\sqrt{P(x)}} \right) \end{pmatrix} = \\ \begin{pmatrix} -\frac{3}{2}t_1 \frac{\alpha}{\Delta} - \frac{1}{12} \frac{d\Delta}{\Delta}, & \frac{3}{2} \frac{\alpha}{\Delta} \\ dt_1 - \frac{1}{6}t_1 \frac{d\Delta}{\Delta} - (\frac{3}{2}t_1^2 + \frac{1}{8}t_2) \frac{\alpha}{\Delta}, & \frac{3}{2}t_1 \frac{\alpha}{\Delta} + \frac{1}{12} \frac{d\Delta}{\Delta} \end{pmatrix} \begin{pmatrix} \int \frac{dx}{\sqrt{P(x)}} \\ \int \frac{x dx}{\sqrt{P(x)}} \end{pmatrix}$$

where

$$\Delta := 27t_3^2 - t_2^3, \quad \alpha := 3t_3 dt_2 - 2t_2 dt_3.$$

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The above data is the Gauss-Manin connection of the family of elliptic curves $y^2 = P(x)$ before the invention of cohomology theories (before 1900).

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We are looking for parameters $t_1(\tau), t_2(\tau), t_3(\tau)$ such that

$$\int \frac{dx}{\sqrt{P(x)}} = a\tau + b$$
$$\int \frac{x dx}{\sqrt{P(x)}} = -b$$

where a, b are two constants which do not depend on τ . This happens if and only if t_1, t_2, t_3 satisfies the differential equation

Ramanujan differential equation:²

$$R : \left\{ \begin{array}{l} \dot{t}_1 = t_1^2 - \frac{1}{12} t_2 \\ \dot{t}_2 = 4t_1 t_2 - 6t_3 \\ \dot{t}_3 = 6t_1 t_3 - \frac{1}{3} t_2^2 \end{array} \right. , \quad \cdot := \frac{\partial}{\partial \tau}$$

Halphen property:³

If t_1, t_2, t_3 is a solution of the Ramanujan differential equation then for any element in

$$\mathrm{SL}(2, \mathbb{C}) := \left\{ \begin{pmatrix} a & b \\ c & d \end{pmatrix} \mid a, b, c, d \in \mathbb{C}, ad - bc = 1 \right\}$$

the functions

$$(c\tau + d)^{-2} t_1 \left(\frac{a\tau + b}{c\tau + d} \right) - c(cz + d)^{-1},$$

$$(cz + d)^{-4} t_2 \left(\frac{a\tau + b}{c\tau + d} \right), (cz + d)^{-6} t_2 \left(\frac{a\tau + b}{c\tau + d} \right)$$

are also coordinates of a solution of R.

³George Henri Halphen (1844-1889)

Transcendency of solutions vs. transcendency of numbers:

(M. 2008) For any point $t \in \mathbb{C}^3 \setminus \{27t_3^2 - t_2^3 = 0\}$ and L_t the solution of R through t , the set $\bar{\mathbb{Q}}^3 \cap L_t$ is either empty or it has only one element. In other words, every solution contains at most one point with algebraic coordinates.

Write each t_i as a formal power series in $q := e^{2\pi i \tau}$,
 $t_i = \sum_{n=0}^{\infty} t_{i,n} q^n$ and substitute in the above differential equation. We will get a recursion.

$$\dot{t} = 12q \frac{\partial t}{\partial q}$$

Initial values

$$t_{1,0} = 1, \quad t_{1,1} = -24$$

Eisenstein series:

After calculating some coefficients and consulting the encyclopedia of integer sequences we may conjecture that t_i 's are well-known Eisenstein series:

$$t_i = a_i \left(1 + b_i \sum_{n=1}^{\infty} \sigma_{2i-1}(n) q^n \right), \quad i = 1, 2, 3, \quad (1)$$

where

$$(b_1, b_2, b_3) = (-24, 240, -504), \quad (a_1, a_2, a_3) = (1, 12, 8).$$

$$\sigma_k(n) := \sum_{d|n} d^k.$$

Modular forms:

1. Monstrous moonshine conjecture:

$$j = 1728 \frac{E_4^3}{E_4^3 - E_6^2} = q^{-1} + 744 + 196884q + 21493760q^2 + \dots$$

Modular forms:

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Let $\eta(q) := \frac{E_4^3 - E_6^2}{1728} = q \prod_{i=1}^{\infty} (1 - q^n)^{24}$.

2. Arithmetic modularity theorem:

$$\eta(q)^2 \eta(q^{11})^{12} = q - 2q^2 - q^3 + 2q^4 + q^5 + 2q^6 - 2q^7 - 2q^9 - 2q^{10}$$

attached to the elliptic curve:

$$E : y^2 + y = x^3 - x^2$$

A generalization of Ramanujan differential equation:

A generalization of Ramanujan differential equation:

$$\left\{ \begin{array}{l} \dot{t}_0 = \frac{1}{t_5}(6 \cdot 5^4 t_0^5 + t_0 t_3 - 5^4 t_4) \\ \dot{t}_1 = \frac{1}{t_5}(-5^8 t_0^6 + 5^5 t_0^4 t_1 + 5^8 t_0 t_4 + t_1 t_3) \\ \dot{t}_2 = \frac{1}{t_5}(-3 \cdot 5^9 t_0^7 - 5^4 t_0^5 t_1 + 2 \cdot 5^5 t_0^4 t_2 + 3 \cdot 5^9 t_0^2 t_4 + 5^4 t_1 t_4 + 2 t_2 t_3) \\ \dot{t}_3 = \frac{1}{t_5}(-5^{10} t_0^8 - 5^4 t_0^5 t_2 + 3 \cdot 5^5 t_0^4 t_3 + 5^{10} t_0^3 t_4 + 5^4 t_2 t_4 + 3 t_3^2) \\ \dot{t}_4 = \frac{1}{t_5}(5^6 t_0^4 t_4 + 5 t_3 t_4) \\ \dot{t}_5 = \frac{1}{t_5}(-5^4 t_0^5 t_6 + 3 \cdot 5^5 t_0^4 t_5 + 2 t_3 t_5 + 5^4 t_4 t_6) \\ \dot{t}_6 = \frac{1}{t_5}(3 \cdot 5^5 t_0^4 t_6 - 5^5 t_0^3 t_5 - 2 t_2 t_5 + 3 t_3 t_6) \end{array} \right.$$

Book: Gauss-Manin connection in disguise: Calabi-Yau
modular forms, Surveys of Modern Mathematics, International
Press, Boston.

<http://w3.impa.br/~hossein/myarticles/GMCD-MQCY3.pdf>, 170
pages, 2016.